Merlion: End-to-End Machine Learning for Time Series


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Abstract

We introduce Merlion, an open-source machine learning library for time series. It features a unified interface for many commonly used models and datasets for forecasting and anomaly detection on both univariate and multivariate time series, along with standard pre/post-processing layers. It has several modules to improve ease-of-use, including a no-code visual dashboard, anomaly score calibration to improve interpretability, AutoML for hyperparameter tuning and model selection, and model ensembling. Merlion also provides an evaluation framework that simulates the live deployment of a model in production, and a distributed computing backend to run time series models at industrial scale. This library aims to provide engineers and researchers a one-stop solution to rapidly develop models for their specific time series needs and benchmark them across multiple datasets.

Keywords: time series, forecasting, anomaly detection, machine learning, autoML, ensemble learning, benchmarking, Python, scientific toolkit

1. Introduction

Time series are ubiquitous in monitoring the behavior of complex systems in real-world applications, such as IT operations management, manufacturing, and cybersecurity (Hundman et al., 2018; Mathur and Tippenhauer, 2016; Audibert et al., 2020). Across all these applications, it is important to accurately forecast the trends and values of key metrics and to rapidly and accurately detect anomalies in those metrics.

This work introduces Merlion1, a Python library for time series intelligence. It provides an end-to-end machine learning framework that includes loading and transforming data, building and training models, post-processing model outputs, evaluating model performance, scalable deployment using a distributed back-end, and a clickable visual dashboard for code-free experimentation. It supports unified APIs for a diverse set of machine learning models for forecasting, anomaly detection, and change point detection on both univariate and multivariate time series. Supported models range from classical models like ARIMA to Bayesian methods to deep learning models.

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Several other time series libraries support similar models (Seabold and Perktold, 2010; Taylor and Letham, 2017; Van Looveren et al., 2019; Alexandrov et al., 2020; Jiang, 2021; Hosseini et al., 2021; Herzen et al., 2022). However, Merlion offers the most complete end-to-end solution. In particular, Merlion has the best support for ensembling heterogeneous models, post-processing model outputs, visualizing model performance, and deploying scalable applications using distributed computing.²

2. Design Principles and Key Components

Merlion’s key design principles are modularity, extensibility³, and ease of use. Merlion is divided into five modules that can easily be composed with each other: data, models, post-processing, ensembles & model selection, and evaluation. The codebase is heavily object-oriented, and it leverages powerful base classes to minimize the amount of code needed to extend the library with custom datasets, models, pre/post-processing, or evaluation metrics. These base classes also provide many convenience features including visualization and serialization. Finally, we provide a clickable visual dashboard that enables code-free experimentation, as well as a distributed back-end that uses pySpark (Zaharia et al., 2016) and Kubernetes to deploy time series application at industrial scale.

Data

Merlion’s TimeSeries data structure represents a \(d\)-dimensional time series \(T\) as a collection of univariates \(U^{(1)}, \ldots, U^{(d)}\), where \(U^{(k)} = (t^{(k)}_1, x^{(k)}_1), \ldots, (t^{(k)}_{n_k}, x^{(k)}_{n_k})\). This reflects the reality that individual univariates may be sampled at different rates, or contain missing data at different timestamps. Users can create TimeSeries objects directly from files on disk, pandas dataframes, or Spark distributed datasets. We also provide standardized loaders for a wide range of datasets in the ts_datasets package.

After the data is loaded, the merlion.transform module lets users pre-process their data in various ways that can make it easier to model. These include resampling, normalization, moving averages, temporal differencing, and many others. Users may also extend this module with other data processing tools (Christ et al., 2018; Law, 2019). Multiple transforms can be composed with each other (e.g. resampling followed by a moving average), and transforms can be inverted (e.g. the normalization \(f(x) = (x - \mu)/\sigma\) is inverted as \(f^{-1}(y) = \sigma y + \mu\)). All models have a model.transform which is automatically applied to any input data.

Models

Merlion provides unified APIs for a wide array of forecasting and anomaly detection models. These include statistical methods, tree-based models, deep learning approaches, and others. We also provide easy-to-use autoML for automatic hyperparameter selection.

All models are initialized with a config object that contains implementation-specific hyperparameters, and support a model.train(time_series) method. Given a general multivariate time series \(T = (U^{(1)}, \ldots, U^{(d)})\), forecasters predict the values of a single target univariate \(U^{(k)}\). One can obtain a model’s forecast of \(U^{(k)}\) by calling model.forecast(time_stamps). Analogously, one can obtain an anomaly detector’s sequence of anomaly scores by calling model.get_anomaly_score(time_series). Forecasters can be used for anomaly detection by treating the residual between the true and predicted value of a target \(U^{(k)}\) as an anomaly score. We implement change point detection as a specific instance of anomaly detection.

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². See Merlion’s README file for a more detailed comparison.
³. See Merlion’s contributing guidelines for detailed information about extending Merlion.
All models can also condition their predictions on historical data without having to be re-trained from scratch, by calling `model.forecast(time_stamps, time_series_prev)` or `model.get_anomaly_score(time_series, time_series_prev)`. Finally, many forecasters support *exogenous regressors*, variables whose future values are known a priori, by calling `model.forecast(time_stamps, exog_data=exog_data)`.

**Post-Processing** All anomaly detectors have a `post_rule` which applies *calibration* and *thresholding* to their outputs. Calibration, a feature unique to Merlion, uses optimal transport to ensure that the anomaly scores follow a standard normal distribution, ensuring that they are both interpretable and consistent across different models. Intelligent thresholding rules reduce a model’s false positive rate suppressing redundant alerts. A user can obtain post-processed anomaly scores from a model by calling `model.get_anomaly_label(time_series)`.

We refer an interested reader to Bhatnagar et al. (2021, Section 4.2) for more details.

**Ensembles and Model Selection** Ensembles are structured as a model that represents a combination of multiple underlying models. For this purpose we have a base `EnsembleBase` class that abstracts the process of obtaining predictions $Y_1, \ldots, Y_m$ from $m$ underlying models on a single time series $T$, and a `Combiner` class that then combines results $Y_1, \ldots, Y_m$ into the output of the ensemble. These combinations include traditional mean ensembles, as well as model selection based on evaluation metrics like sMAPE. Subclasses implement the `forecast` or `get_anomaly_score` methods, and their `train` method automatically handles dividing the data into training and validation splits if performing model selection.

Since most anomaly detectors return vastly different scores, Merlion uses calibration to transform these scores into standard normal random variables. These calibrated scores can then be combined with a simple mean. Merlion is thus the only library to support ensembles of heterogeneous anomaly detectors. See Bhatnagar et al. (2021, Section 4.3) for more details.

**Evaluation** When a time series model is deployed live in production, training and inference are rarely performed in batch on a full time series. Rather, the model is re-trained at a regular cadence, and where possible, inference is performed in a streaming mode. Merlion’s evaluation framework simulates this workflow to obtain predictions from a model that more closely mirror real-world scenarios. We also implement a wide range of evaluation metrics for both forecasting or anomaly detection which conform to a unified interface, and we provide scripts which allow users to easily evaluate model performance on any dataset included in the `ts_datasets` module, as well as custom datasets provided by the user.

**Additional Interfaces** To ease initial experimentation, Merlion provides a unique no-code visual dashboard which allows users to try different models on custom datasets, and view both quantitative and qualitative evaluations in a single window. Merlion also provides a distributed computing backend using PySpark, which makes it easy to deploy any Merlion model at industrial scale. Only one other library has a distributed backend, and its scope is limited to just a few forecasting models (Garza, 2021).

### 3. Experiments

In this section, we use Merlion to benchmark the performance of various models on both forecasting (Table 1) and anomaly detection (Table 2). The purpose of this section is not
Table 1: Mean sMAPE achieved by univariate forecasting models on M4 (Makridakis et al., 2018) and 3 internal datasets. We compare ARIMA, Prophet (Taylor and Letham, 2017), ETS, and MSES (Cassius et al., 2021), and our own AutoML variants of ARIMA, Prophet, and ETS. Best results are in bold.

<table>
<thead>
<tr>
<th>Model</th>
<th>m4-hour</th>
<th>m4-day</th>
<th>m4-week</th>
<th>m4-month</th>
<th>m4-quarter</th>
<th>m4-year</th>
<th>internal1</th>
<th>internal2</th>
<th>internal3</th>
</tr>
</thead>
<tbody>
<tr>
<td>MSES</td>
<td>32.45</td>
<td>5.87</td>
<td>16.53</td>
<td>25.40</td>
<td>19.03</td>
<td>21.63</td>
<td>33.50</td>
<td>32.30</td>
<td>3.882</td>
</tr>
<tr>
<td>ARIMA</td>
<td>33.54</td>
<td>3.23</td>
<td>9.29</td>
<td>17.66</td>
<td>13.37</td>
<td>17.04</td>
<td>21.64</td>
<td>24.00</td>
<td>5.94</td>
</tr>
<tr>
<td>Prophet</td>
<td>18.08</td>
<td>11.67</td>
<td>19.98</td>
<td>20.64</td>
<td>24.53</td>
<td>30.23</td>
<td>56.07</td>
<td>30.93</td>
<td>72.55</td>
</tr>
<tr>
<td>ETS</td>
<td>42.95</td>
<td>3.04</td>
<td>14.32</td>
<td>11.08</td>
<td>16.43</td>
<td>17.02</td>
<td>25.10</td>
<td>3.55</td>
<td>3.55</td>
</tr>
<tr>
<td>AutoARIMA</td>
<td>13.61</td>
<td>3.29</td>
<td>8.30</td>
<td>14.26</td>
<td>10.51</td>
<td>15.98</td>
<td>17.45</td>
<td>5.94</td>
<td>3.42</td>
</tr>
<tr>
<td>AutoProphet</td>
<td>16.49</td>
<td>11.67</td>
<td>20.01</td>
<td>24.62</td>
<td>30.23</td>
<td>56.43</td>
<td>26.35</td>
<td>69.32</td>
<td>3.15</td>
</tr>
</tbody>
</table>

Table 2: F1 scores achieved by univariate anomaly detection models. The ensemble takes the mean calibrated anomaly scores of AutoETS, RRCF, and ZMS. We also report the average gap (over datasets) in F1 between each model and the best model. Best results are in bold.

<table>
<thead>
<tr>
<th></th>
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</tr>
</thead>
<tbody>
<tr>
<td>ARIMA</td>
<td>0.531</td>
<td>0.395</td>
<td>0.227</td>
<td>0.313</td>
<td>0.148 ± 0.099</td>
</tr>
<tr>
<td>AutoETS</td>
<td>0.296</td>
<td>0.350</td>
<td>0.309</td>
<td>0.334</td>
<td>0.245 ± 0.042</td>
</tr>
<tr>
<td>AutoProphet</td>
<td>0.344</td>
<td>0.323</td>
<td>0.310</td>
<td>0.418</td>
<td>0.166 ± 0.062</td>
</tr>
<tr>
<td>Isolation Forest (Liu et al., 2008)</td>
<td>0.436</td>
<td>0.244</td>
<td>0.347</td>
<td>0.461</td>
<td>0.142 ± 0.111</td>
</tr>
<tr>
<td>RRCF (Guha et al., 2016)</td>
<td>0.248</td>
<td>0.317</td>
<td>0.314</td>
<td>0.568</td>
<td>0.148 ± 0.132</td>
</tr>
<tr>
<td>Spectral Residual (Ren et al., 2019)</td>
<td>0.340</td>
<td>0.153</td>
<td>0.338</td>
<td>0.469</td>
<td>0.189 ± 0.150</td>
</tr>
<tr>
<td>WindStats (ours, baseline)</td>
<td>0.225</td>
<td>0.247</td>
<td>0.324</td>
<td>0.396</td>
<td>0.239 ± 0.114</td>
</tr>
<tr>
<td>ZMS (ours, baseline)</td>
<td>0.486</td>
<td>0.290</td>
<td>0.427</td>
<td>0.594</td>
<td>0.129 ± 0.094</td>
</tr>
<tr>
<td>Ensemble (ours)</td>
<td>0.500</td>
<td>0.548</td>
<td>0.396</td>
<td>0.476</td>
<td>0.034 ± 0.044</td>
</tr>
</tbody>
</table>

4. Conclusion

We introduce Merlion, an open-source machine learning library for time series, which is designed to address many of the pain points in today’s industry workflows for time series anomaly detection and forecasting. It provides unified, easily extensible interfaces and implementations for a wide range of models and datasets, an autoML module that consistently improves the performance of multiple forecasting models, post-processing rules for anomaly detectors that improve interpretability and reduce the false positive rate, and transparent support for ensembles that robustly achieve good performance on multiple benchmark datasets. These features are tied together in a flexible pipeline that quantitatively evaluates the performance of a model, and a visualization module for qualitative analysis.


